

# COMP 761: Lecture 27 – Max Flow

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November 6, 2020

## Problem

A *cut* in a flow network is a partition of the vertices into  $S$  and  $T$ , where  $s \in S$  and  $t \in T$ . The *capacity* of the cut  $(S, T)$  is:

$$c(S, T) = \sum_{u \in S} \sum_{v \in T} c(u, v).$$

Prove that  $|f| \leq c(S, T)$  for any flow  $f$  and cut  $(S, T)$ .

*(Please don't post your ideas in the chat just yet, we'll discuss the problem soon in class.)*

# Course Announcements

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- On Problem 1, reminder not just to cite that polynomials are  $\Theta(\text{leading term})$  unless you prove that. May want to provide a constant  $c$  for  $\Omega$  notation explicitly. If this was not clear to you, feel free to take an additional 24 hours before submitting (you can edit an existing submission). Slack message with any questions.



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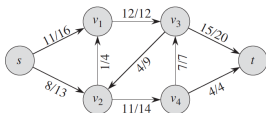
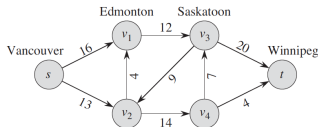
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$$f(u, v) \leq c(u, v)$$

and  $f(u, v) = 0$  if there is no edge  $(u, v)$ , and where for all  $u$  different from  $s$  and  $t$ ,

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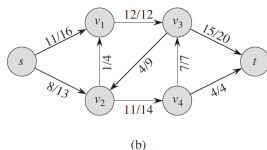
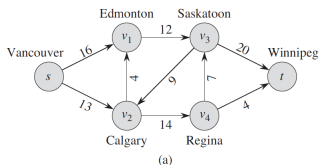
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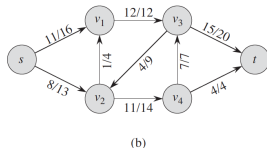
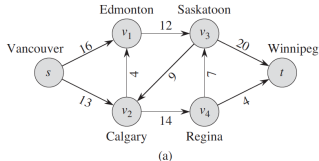
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- We say that the *value*  $|f|$  of a flow  $f$  is defined by:

$$|f| = \sum_v f(s, v) - \sum_v f(v, s).$$

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- (There might be several with this maximum value.)
- Applications include routing shipments, calculating flow of water or electricity, airplane scheduling, image segmentation, etc.

# Antiparallel edges



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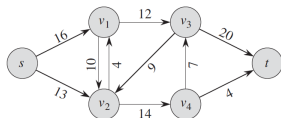
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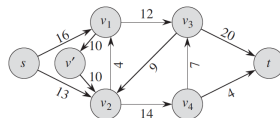
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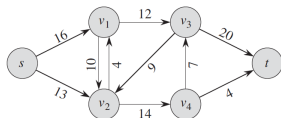
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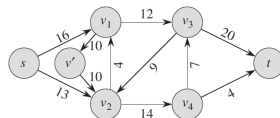
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(b)

- Note that we can't just “cancel” the antiparallel capacities, since that would prevent us traveling in one direction along that edge.

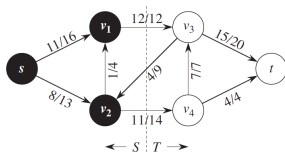
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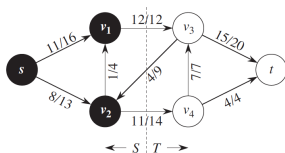
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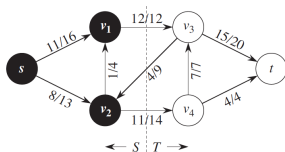
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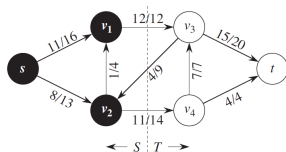
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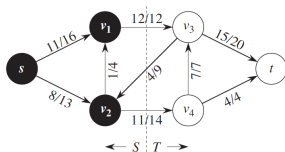
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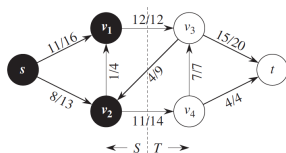
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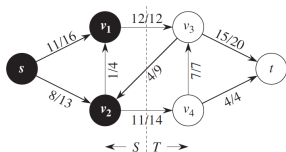


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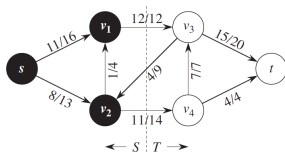


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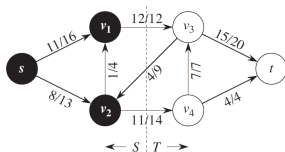
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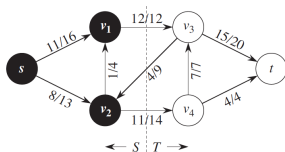
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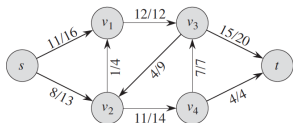
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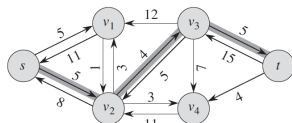
- Given a flow network  $G$  and a flow  $f$  in it, we can define the *residual network*  $G_f$  as follows:
- If  $(u, v)$  is an edge in  $G$ , then both  $(u, v)$  and  $(v, u)$  are edges in  $G_f$ , with *residual capacities*

$$c_f(u, v) = c(u, v) - f(u, v)$$

$$c_f(v, u) = f(u, v).$$



(a)

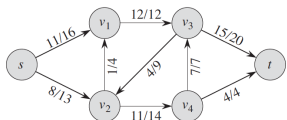


(b)

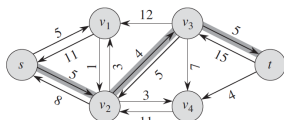
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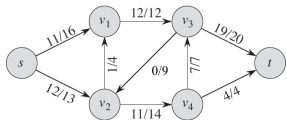
- Given a flow network  $G$  and a flow  $f$  from  $s$  to  $t$ , an *augmenting path* is a path from  $s$  to  $t$  in the residual network with positive capacity along all edges.



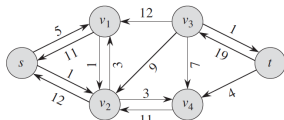
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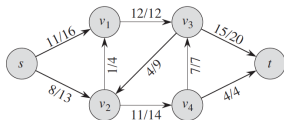


(c)

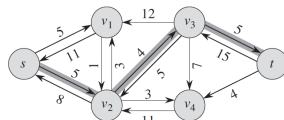


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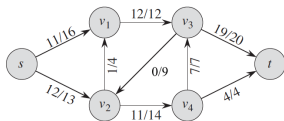
# Ford-Fulkerson method



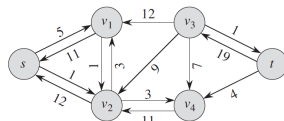
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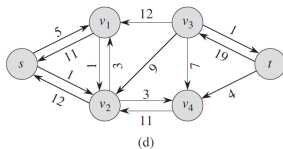
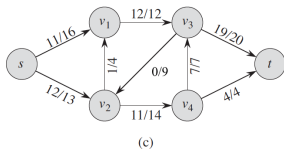
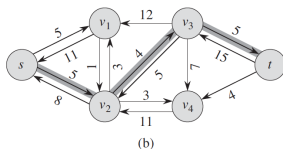
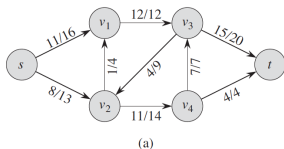


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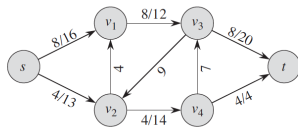
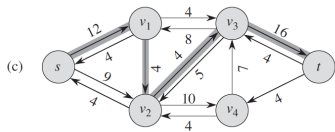
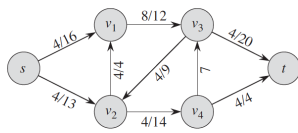
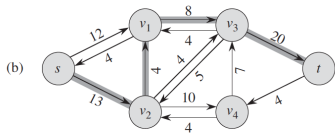
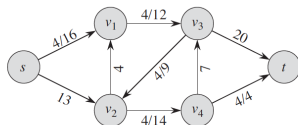
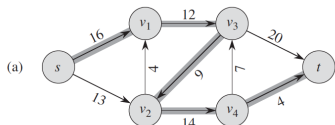
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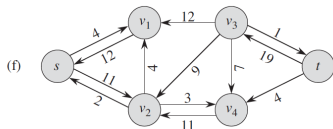
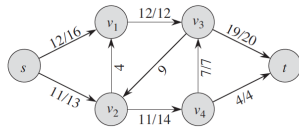
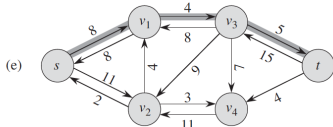
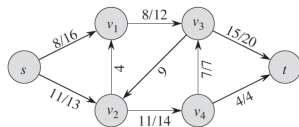
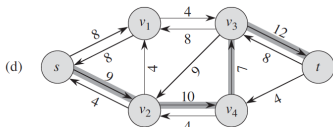
- The *Ford-Fulkerson method* for solving max flow consists of:
  - 1 Start out with  $f(u, v) = 0$  everywhere.
  - 2 Find an augmenting path in the residual network  $G_f$ .
  - 3 Update  $f$  by adding flow along that path.
  - 4 Repeat Steps 2 and 3 until there is no augmenting path.



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- Why does (3) imply (1)?
- We know  $|f| \leq c(S, T)$  for every flow  $f$ , so if  $|f| = c(S, T)$ , then  $f$  must be maximum.

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$$\begin{aligned} |f| &= f(S, T) = \sum_{u \in S} \sum_{v \in T} (f(u, v) - f(v, u)) \\ &= \sum_{u \in S} \sum_{v \in T} (c(u, v) - 0) \end{aligned}$$

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- This shows that the Ford-Fulkerson method will eventually give us a max flow.

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- An improvement in the algorithm (the Edmonds-Karp algorithm) can actually make it:

$$O(|V| \cdot |E|^2).$$